



**ZR-DC/PCB DC Receiver  
Installation Instructions**

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**IMPORTANT**

The first few pages of these instructions contain important information on safety and product conformity. Please read, and ensure that you understand this information before continuing.

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**CONTENTS**

<b>Product Safety</b> .....	4
<b>Electromagnetic Compatibility (EMC)</b> .....	4
General connector layout .....	5
Introduction .....	6
Unpacking .....	6
Supply Connections .....	7
Connecting the Pan/Tilt head and Auxiliaries .....	7
Connecting the Lens .....	8
Connecting the Preset Feedback Potentiometers .....	8
Pan and Tilt head feedback potentiometers .....	9
Connecting the Telemetry .....	10
Connecting the Video .....	10
Connecting the Alarm Inputs .....	10
Connecting the Alarm Output Relay .....	10
Switch Settings - Lens .....	11
Switch Settings - Auxiliary output relays .....	11
Switch Settings - Auxiliaries .....	12
Switch Settings - Creep Speed .....	
Switch Settings - Auto Pan or Tour .....	12
Testing and Commissioning .....	13
Testing the Video and Telemetry Reception .....	13
Video Gain and Lift Adjustment .....	13
Testing the Pan/Tilt head, Lens and Presets .....	14
Setting up the Presets .....	14
Fuse Replacement .....	14
Specifications .....	15

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**PRODUCT SAFETY**

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Please follow these instructions as you install your ZR-DC/PCB. If you encounter any problems contact Baxall Limited.

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**IMPORTANT NOTE**

The power supplies of the ZR-DC/PCB receiver are designed to power the receiver itself and to provide outputs for lens drives, pan and tilt drives etc. Under no circumstances should any other equipment such as cameras, heaters, fans, interface converters etc. derive their power directly from your ZR-DC/PCB receiver. Incorrect use of the receiver in this manner may cause damage and invalidate your warranty.

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**⚠ WARNING**

Installation is only to be carried out by competent, qualified and experienced personnel. Wire in accordance with the country of installations' National Wiring regulations. Failure to do so can result in death or injury by electric shock. A means of disconnecting the receiver from the mains supply must be provided as part of the installation and must be situated close by.

**BEFORE UNDERTAKING ANY INSTALLATION OR MAINTENANCE, THE RECEIVER MUST BE DISCONNECTED FROM THE MAINS SUPPLY.**

Your ZR-DC/PCB circuit boards must be installed in accordance with an approved standard e.g. BSEN60950. All external wiring must be in accordance with an internationally recognised standard.

All hazardous voltages must be protected from the user and adequate warnings must be fitted to the final assembly.

Under no circumstances must the specifications of the product be exceeded.

The circuit boards must be enclosed within a housing rated to IP65 or better if the product is to be used in an outdoor environment, or an indoor environment likely to be wet.

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**ELECTROMAGNETIC COMPATIBILITY (EMC)**

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**The ZR-DC/PCB is supplied as a component performing a direct function for incorporation into apparatus. This component is not intended for direct public use and is therefore excluded from CE marking or from any EC declaration by the manufacturer.**

The ZR-DC/PCB is designed for general purpose CCTV applications within a residential, commercial or light industrial environment.

The main printed circuit board must be securely mounted to a ground plane at earth potential (such as an earthed metal baseplate), using the mounting holes provided. The circuit board must not be located in proximity to high levels of radio frequency or magnetic fields.

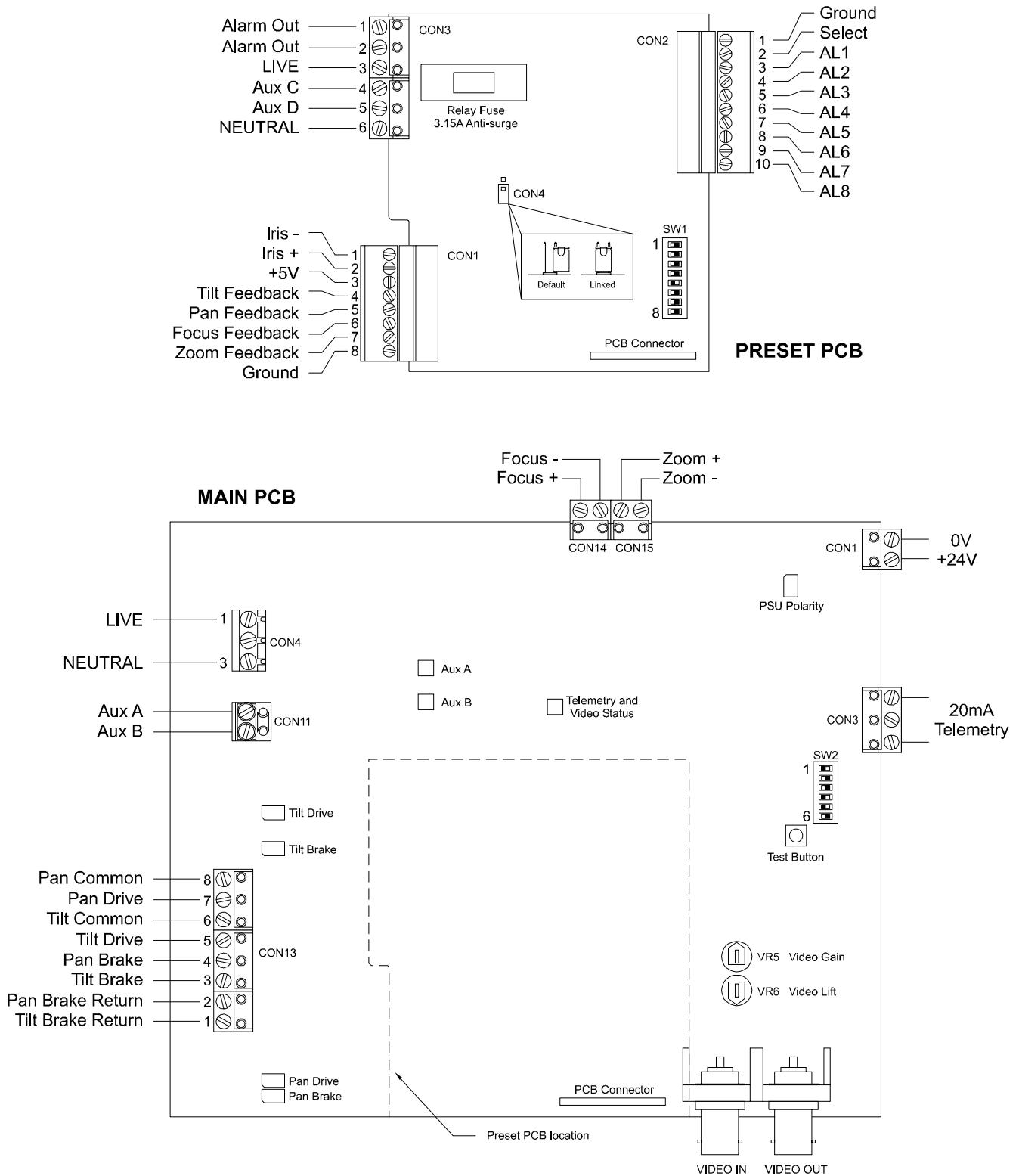
The circuit boards must be protected from casual Electrostatic Discharge (ESD), and be installed using anti-static precautions.

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GENERAL CONNECTOR LAYOUT

Shown below are the locations of the connectors, switches, LEDs, fuses etc. on the main and preset printed circuit boards. Although shown separately for clarity, the preset PCB is usually mounted above the main PCB in the position indicated by the dotted line.

Figure 1

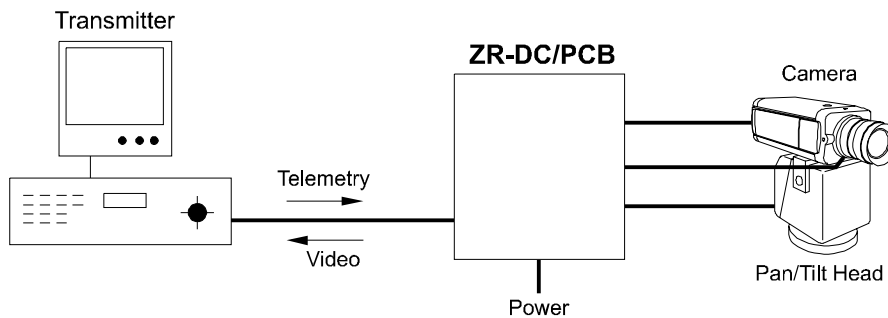


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**INTRODUCTION**

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The diagram below shows an example of a telemetry system. Your ZR-DC/PCB receiver is a Closed Circuit TV (CCTV) component which receives instructions from a remote transmitter and translates them into Pulse Width Modulated (PWM) DC control signals and DC lens drive signals.



Your ZR-DC/PCB receiver takes as its control input a Baxall 20mA twisted-pair telemetry signal or a Baxall coaxial telemetry signal (where telemetry signals and video signals share the same coaxial cable). The ZR-DC/PCB can drive a DC Pan/Tilt head, four auxiliaries and three lens functions (zoom, focus and iris).

Your ZR-DC/PCB can store eight preset positions, each with an associated alarm input. Also linked to the alarm inputs is a volt-free alarm output relay which closes for one second for each new alarm condition. In addition, a software driven auto pan or preset tour function is provided.

**Note:** In order for the auto pan and preset tour functions to operate correctly, the video from the camera must be routed through the receiver PCB.

Your ZR-DC/PCB also contains a video amplifier, with gain and high-frequency lift. This can improve video transmission and telemetry reception over longer cable runs.

The ZR-DC/PCB requires a separate 240V AC to 24V DC power supply (Baxall part number ZR-DC/PSU).

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**UNPACKING**

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Keep your packaging for use if your DC receiver is stored for a time or needs to be returned for whatever reason. The packaging should contain:

- The ZR-DC/PCB consisting of the main board and preset board
- These instructions

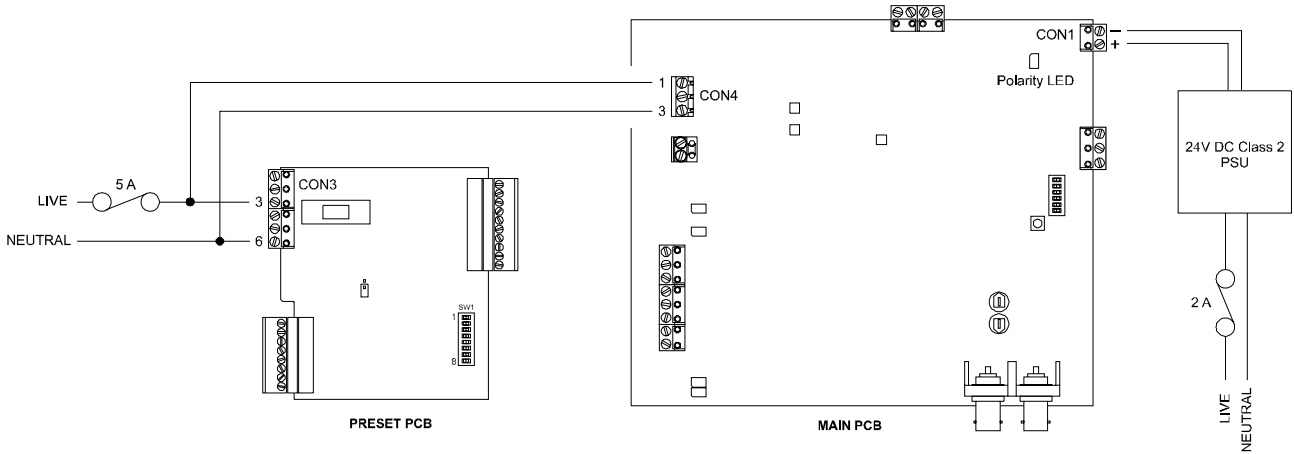
Please inform your suppliers and carriers immediately if the product is damaged or any part is missing. Do not attempt to use it.

SUPPLY CONNECTIONS

**⚠ WARNING**

**SWITCH OFF ALL THE POWER BEFORE CONNECTING THE RECEIVER. YOUR RECEIVER MUST BE EARTHED. THE PROTECTIVE EARTH CONNECTION MUST BE MADE BEFORE CONNECTING MAINS VOLTAGES. A MEANS OF DISCONNECTING THE RECEIVER FROM THE MAINS SUPPLY MUST BE PROVIDED AS PART OF THE INSTALLATION AND MUST BE SITUATED CLOSE BY.**

Your ZR-DC/PCB requires a connection to a 24V DC supply (Baxall part number ZR-DC/PSU) and connection to a 240V AC supply. Typical connections are shown below. The 240V AC connection is switched by internal relays to supply any auxiliary devices operated by the system. Correct connection of the 24 V DC  $\pm 10\%$  power supply is indicated by the LED. Red indicates reverse polarity, green indicates the correct polarity.



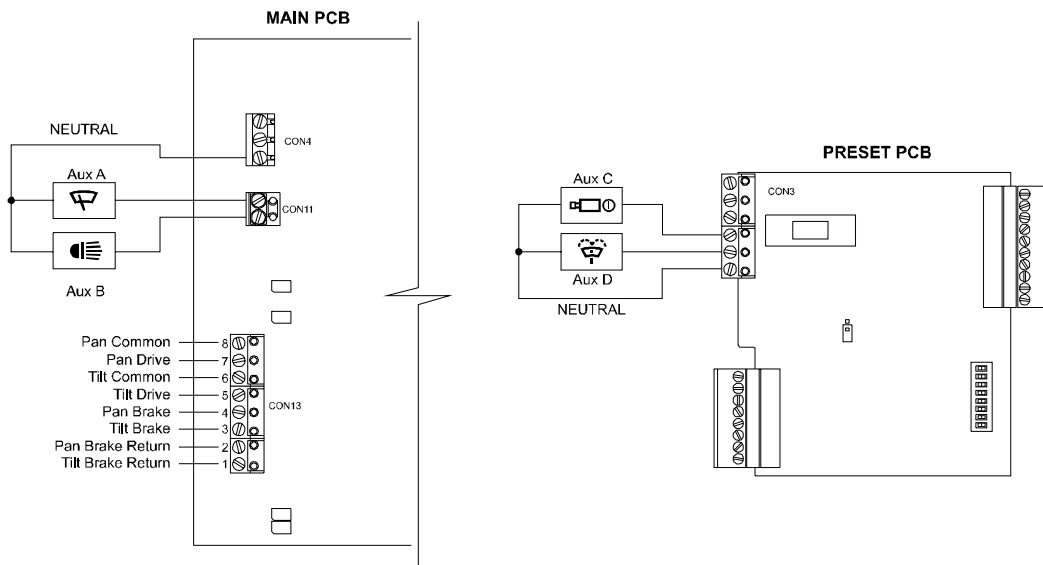
Typical Connections

CONNECTING THE PAN/TILT HEAD AND AUXILIARIES

Referring to the instructions for your Pan/Tilt head and auxiliaries, connect them according to the schematic below. The Auxiliaries A, B, C and D may be configured using SW1 and SW2. They are shown in the schematic in their default states.

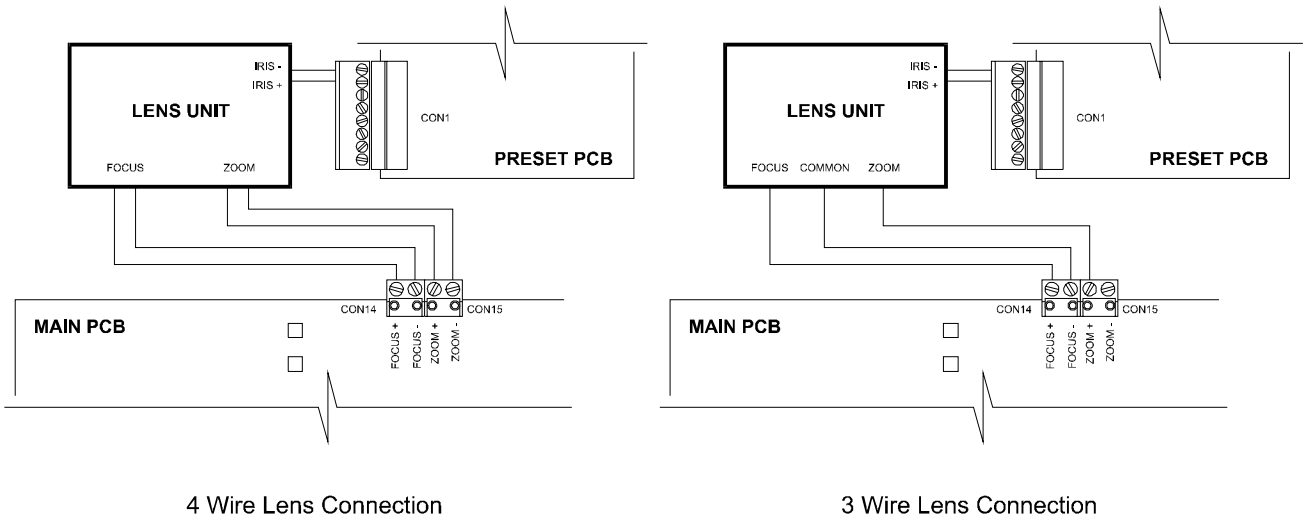
**⚠ CAUTION**

**Maximum current is 750mA per relay. Infrared lamps will exceed this so an external slave relay will be necessary.**



**△ CAUTION**

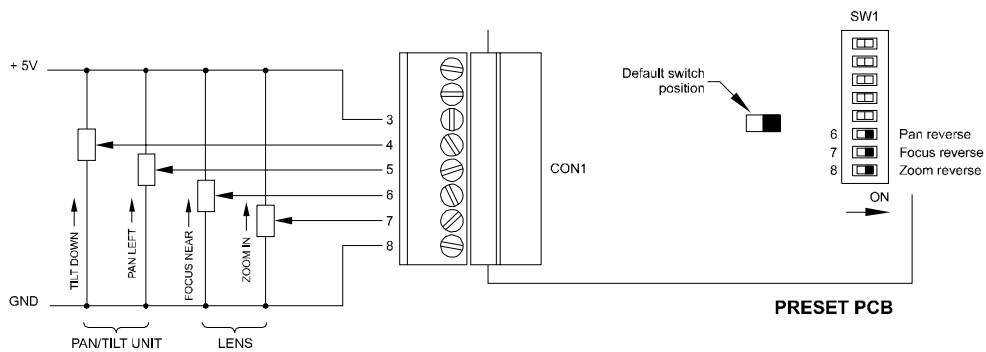
**DO NOT CONNECT ANY LENS CONNECTIONS TO GROUND AS THIS MAY DAMAGE YOUR ZR-DC/PCB. IN PARTICULAR, ENSURE THAT THE LENS COMMON ON A 3 WIRE LENS CONNECTION IS NOT CONNECTED TO GROUND.**



Switch SW2 on the main PCB needs to be set to the type of lens being used - see **Switch Settings - Lens Type**

**CONNECTING THE PRESET FEEDBACK POTENTIOMETERS**

The diagram below shows the default direction for the feedback pots. For example, it shows that as the lens is focused on a nearby object, the focus feedback signal increases towards +5V. The focus, zoom and pan directions can easily be reversed using switches located on the preset PCB. Changing the tilt feedback direction is slightly more complicated so try to wire it correctly now e.g. so that tilt down increases the feedback voltage towards +5V. Refer to the instructions for your lens and Pan/Tilt unit to wire the feedback pots.



The switches SW1/6, SW1/7 and SW1/8 can be used to reverse the operation of the Pan, Focus and Zoom functions simply by changing the switch to its opposite position.



**⚠ WARNING**

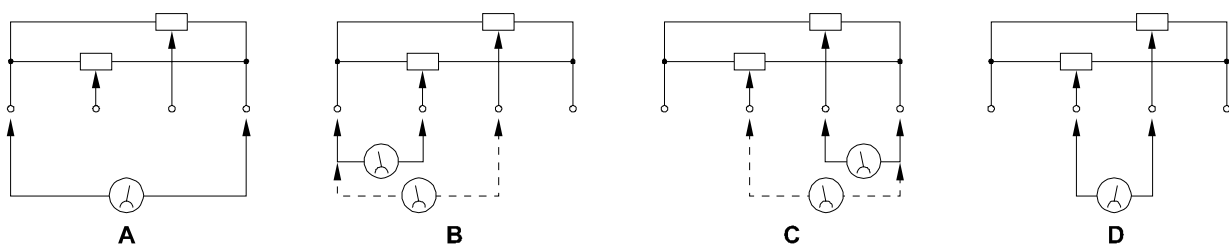
**DANGER OF ELECTRIC SHOCK. SWITCH OFF POWER BEFORE ALTERING ANY PAN AND TILT HEAD CONNECTIONS**

**Determining the supply connections**

The supply connections to the feedback potentiometers can be identified using a Digital Voltmeter (DVM) set to measure resistance as follows.

Connect the DVM to any two of the four wires. Actuate both the pan and tilt functions and observe the changes in the resistance readings of the DVM. The DVM will be connected according to the table below.

Observations	Connection
No resistance change when <b>both</b> pan and tilt are actuated	A
Resistance reading is changed by pan <b>or</b> tilt actuation (not both)	B or C
Resistance reading <b>changes</b> when both pan and tilt are actuated	D



When the DVM is connected according to A above, the supply wires have been correctly identified. Connect the supply wires to the preset PCB as follows: Positive supply wire to CON 1 terminal 3, Negative supply wire to CON 1 terminal 8.

**Determining the pan and tilt potentiometers**

Connect the DVM to one of the remaining two wires and the negative supply connection. Actuate the pan function only and see if the measured resistance changes. If the resistance changes, the wire is connected to the pan feedback potentiometer, if it doesn't the wire is connected to the tilt potentiometer. Confirm this by actuating the tilt function and checking the resistance changes with respect to the negative supply connection. Connect the wires to CON 1 according to the following: Pan potentiometer to terminal 7, Tilt potentiometer to terminal 6.

**Checking correct feedback potentiometer operation**

Set the DVM to measure voltage (e.g. 0 to 20V DC) and connect it across the negative supply connection and the tilt potentiometer connection (CON 1 terminal 8 and CON 1 terminal 6) Operate the tilt function. The voltage measured should decrease towards 0V as the pan and tilt head is tilted **up**, and towards 5V as the head is tilted **down**. If the opposite occurs, the supply connections are probably incorrect. Exchange the CON 1 terminal 3 and CON 1 terminal 8 connections with each other.

Next, check the pan function by connecting the DVM across the negative supply and pan potentiometer terminals (CON 1 terminal 8 and CON 1 terminal 7). As the head is panned to the **left**, the voltage measured should increase towards 5V. As the head is panned to the **right**, the voltage measured should decrease towards 0V. If the opposite occurs, use the mode reversal switch on the preset PCB (SW1, switch 6) to reverse the pan function operation.

**Testing**

Set up a preset position using the telemetry transmitter according to its instructions, and check the operation and accuracy of the preset. If all is well, use the same methods to determine the zoom and focus feedback connections.

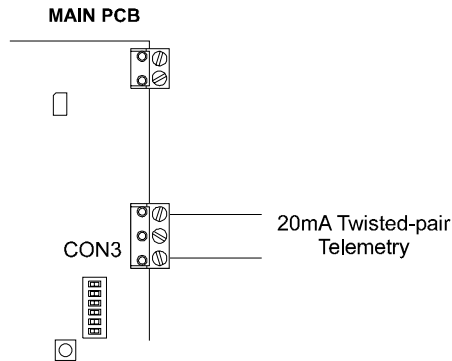
*Note: If after making the zoom and focus connections **both** the pan and tilt feedback potentiometers do not operate correctly, try reversing the lens feedback supply connections.*

**CONNECTING THE TELEMETRY**

You can use either coaxial or twisted pair telemetry with your ZR-DC/PCB. It switches automatically to the type of telemetry it first receives after the power is applied.

**Twisted-pair Telemetry**

Connect Baxall 20 mA twisted pair telemetry to CON 3 on the main PCB. Either polarity is accepted.



**Coaxial Telemetry**

Baxall coaxial telemetry is connected as the video connections are made. Note that you can still connect the video through the PCB if you use twisted-pair telemetry.

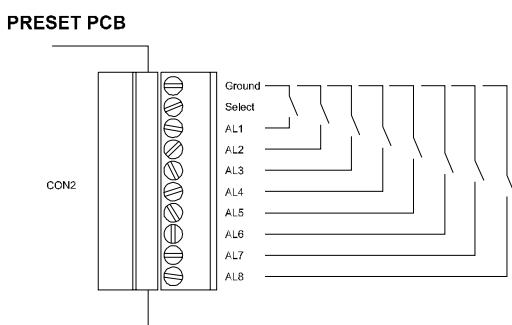
**CONNECTING THE VIDEO**

Connect all video using 75 ohm video coaxial cable terminated by BNC connectors. Connect the camera to VIDEO IN, and the transmitter to VIDEO OUT.

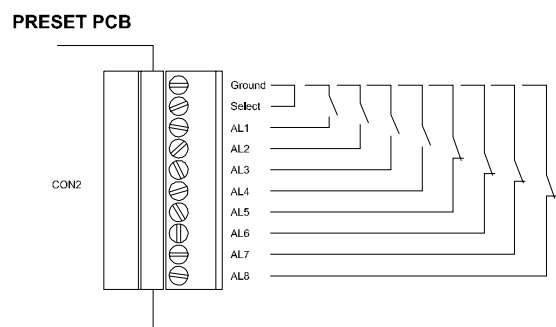
**Note:** In order for the auto pan and preset tour functions to operate correctly, the video from the camera must be routed through the receiver PCB.

**CONNECTING THE ALARM INPUTS**

Your ZR-DC/PCB has 8 alarm inputs. The alarm inputs are split into two banks. Alarm inputs 1 to 4 are always configured as normally open (N/O). Alarm inputs 5 to 8 are configured as normally open unless the select terminal (SEL) is connected to ground. In this case they become normally closed (N/C).



Alarm Inputs with Select floating



Alarm Inputs with Select connected to Ground

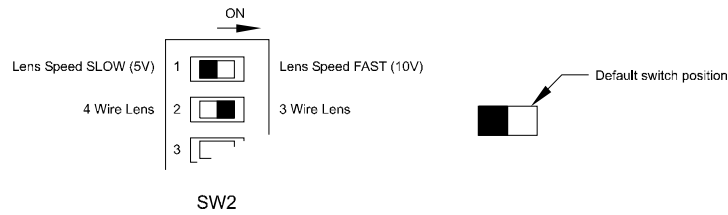
*Note: When AL5 to AL8 are configured as normally closed, any unused alarm inputs must be connected to ground to ensure correct operation.*

**CONNECTING THE ALARM OUTPUT RELAY**

A normally open, volt-free relay contact is provided for alarm output purposes. This relay contact closes for approximately one second for each new alarm condition. The relay is rated for a maximum of 3A at 240V AC.

**SWITCH SETTINGS - LENS**

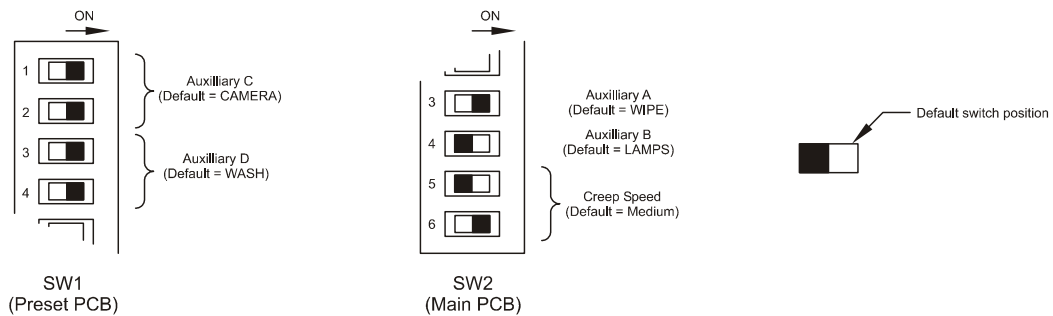
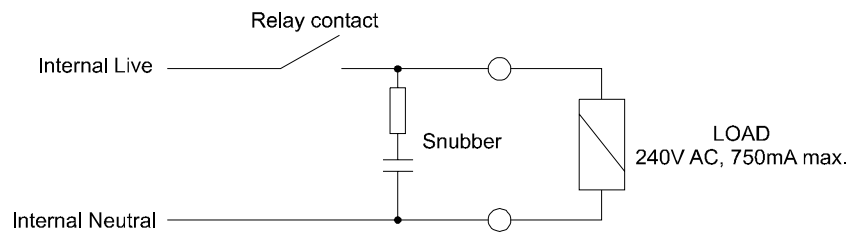
Switches 1 and 2 of the 6 way dip-switch, SW2 control the Lens speed and the lens type as shown below. The switch is located on the main PCB.



*Note: The iris is independent of whether a 4 wire or 3 wire lens is selected, and also the speed setting of the lens.*

**SWITCH SETTINGS - AUXILIARY OUTPUT RELAYS**

The AUX A, AUX B, AUX C and AUX D relays can be programmed to respond to camera power, wipe, lamps, wash or Aux 4 telemetry commands from the transmitter. The contact configuration is shown below.



Function	AUX A	AUX B	AUX C		AUX D	
	SW2/3	SW2/4	SW1/1	SW1/2	SW1/3	SW1/4
Camera	On	-	Off *	Off *	-	-
Wipe	Off *	-	Off	On	Off	On
Lamps	-	On*	On	Off	-	-
Wash	-	Off	On	On	Off *	Off *
AUX4 †	-	-	-	-	On	Off
AUX4 ‡	-	-	-	-	On	On

Notes: \* indicates default setting.  
 † this function remains on for as long as the key is held.  
 ‡ this function toggles between off and on.  
 Convention SW2/3 = Switch number 3 of dip switch bank SW2.

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**SWITCH SETTINGS - CREEP SPEED**

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Four creep speeds are available for preset recall. When the preset has been recalled, it will ramp up to its top speed then decelerate to the selected creep speed as it approaches the final preset position. Use Switches 5 and 6 of the 6 way dip-switch, SW2 to select the creep speed. Default setting is Medium.

Creep Speed	Switch 2/5	Switch 2/6
Slow	Off	Off
Medium Slow	Off	On
Medium	On *	Off *
Fast	On	On

\* indicates default setting.

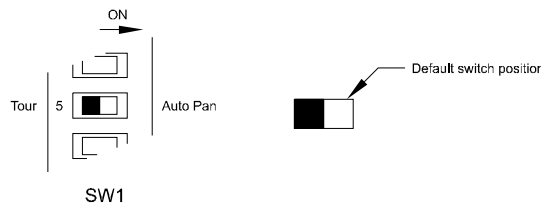
If the Pan/Tilt head stalls on preset recall, increase the creep speed. If the Pan/Tilt head overshoots, decrease the creep speed.

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**SWITCH SETTINGS - AUTO PAN OR TOUR**

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When auto pan (AUX 3) is selected at the transmitter the standard ZR-DC/WBX can operate in one of two pan modes, auto pan or Tour. Auto pan is a software driven function and so does not need a specialised pan and tilt unit. When you operate auto pan the Pan/Tilt head pans for 60 seconds, pauses 15 seconds, pans in the opposite direction, pauses and starts again. If your Pan/Tilt head hits the end-stops, it rests there until the auto pan asks it to return. The Tour function needs feedback potentiometers in the pan and tilt head. It performs a tour of all the stored preset camera positions in numerical order. Preset positions must be defined and stored for the tour function to operate correctly. The default setting is for auto pan.




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*Note: On some transmitters, when auto pan is operating, you must first deselect it before manual control can be regained over the telemetry.*

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**TESTING AND COMMISSIONING**

**⚠ WARNING**

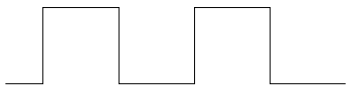
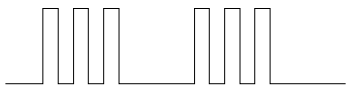
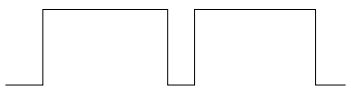
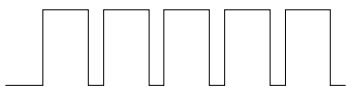
**MAINS VOLTAGES MAY NOW BE PRESENT. THERE IS A RISK OF INJURY OR DEATH BY ELECTRIC SHOCK.**

Check that all connections to your ZR-DC/PCB are correct then switch on the power to your camera, transmitter and ZR-DC/PCB.

**TESTING THE VIDEO AND TELEMTRY RECEPTION**

Your ZR-DC/PCB switches to the type of telemetry it first receives when the power is switched on. You can still use the video connections if you are using twisted-pair telemetry.

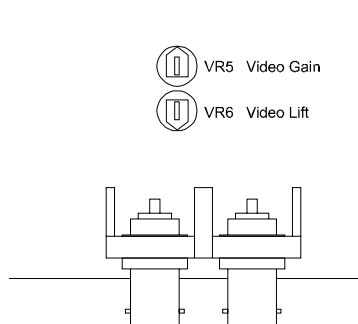
The Telemetry and Video Status LED located on the main PCB (see figure 1) is used to check that both the video and telemetry signals are correct. Correct operation is indicated by a slow regular flash. Other fault conditions are shown below.

LED Indication	Description
Slow Flash 	Correct operation. The video and telemetry signals are operating correctly
Burst 	The unit is not receiving video or telemetry signals
Mostly on 	The unit is receiving video but not telemetry
Fast Flash 	The unit is receiving video and telemetry but the telemetry signal contains errors

If the video signal level is too low when it arrives at the transmitter then the telemetry can lose synchronisation causing DATA ERRORS. To remedy this, adjust the video gain and lift potentiometers as shown below.

**VIDEO GAIN AND LIFT ADJUSTMENT**

Adjustments to the Gain and Lift potentiometers can improve picture quality on the monitor and/or improve coaxial telemetry reception. VR5 is used to adjust the video Gain and VR6 is used to adjust the video Lift. These are factory set to 1 V pk-pk. If you have data errors, try adjusting Gain and Lift to improve the picture quality. When your ZR-DC/PCB is receiving correct telemetry, the Telemetry and Video Status LED will emit a slow regular flash. The location and default setting of VR5 and VR6 is shown below.



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**TESTING THE PAN/TILT HEAD, LENS AND PRESETS**

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The Test Button shown in figure 1 controls the 14 tests. Push and release the button once to enter test 0. Push and release again to increment through each of the tests. The receiver will automatically leave test mode 30 seconds after the last depression of the push-button or after Test 13. While you are in test mode, the Telemetry and Video Status LED remains lit.

Test Number	Action	Test Number	Action
Test 0	Pan Left	Test 9	Wipe
Test 1	Pan Right	Test 10	Camera
Test 2	Tilt Up	Test 11	Lamps
Test 3	Tilt Down	Test 12	Aux 4
Test 4	Zoom Out	Test 13	Preset 1
Test 5	Zoom In	Test 14	Preset 2
Test 6	Focus Out	Test 15	Preset 3
Test 7	Focus In	Test 16	Preset 4
Test 8	Wash		

It is only necessary to test one of the preset positions to ensure that the feedback connections are correct. If they are not then they can be changed by using switches SW1/6, SW1/7, and SW1/8 according to the section **Connecting the Preset Feedback Potentiometers** on page 8.

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**SETTING UP THE PRESETS**

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Most Baxall transmitters access and set the presets by the following method, however on some transmitters the presets can be accessed directly (see your transmitter manual).

1. Move the pan/tilt head to the desired position for this preset.
2. Store the position as preset <n> using the appropriate method for the transmitter or keyboard being used. This is normally done by pressing the following keys in sequence: **F** (the function key), <n> (a number for the preset between 1 and 8), **⊗** (the preset key).
3. Further preset positions may be stored by repeating step 2 above.
4. Preset positions are recalled using the appropriate method for the transmitter or keyboard being used. This is normally done by pressing the number of the preset position to be recalled followed by the **⊗** preset key.
5. Programmed presets can be easily verified by activating the corresponding alarm input, e.g. activating alarm input 5 will recall preset 5.

A link on the preset board (the 2 pin jumper CON 4 shown in figure 1) allows you to disable the presets. When the jumper is shorted, the presets are disabled.

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**FUSE REPLACEMENT**

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**ZR-DC/PCB - Preset board fuse**

The preset PCB is fitted with a protective fuse. If the fuse should fail, it must be replaced with one of identical value and characteristics as follows.

1. DISCONNECT THE SUPPLY.
2. Pull the plastic fuse carrier from the fuse holder located on the PCB.
3. Replace the fuse with a 3.15A, anti-surge, 20mm cartridge type.
4. Replace the fuse holder and reconnect the supply.

**Power Supply**

The ZR-DC/PCB requires 24V DC  $\pm$  10%. Maximum 3A.

**Telemetry Inputs**

Baxall Coaxial Telemetry or 20mA current loop twisted pair to the Baxall Telemetry specification.

**Video Input**

1V peak to peak composite video via 75 ohm BNC connector

**Video Output**

1V peak to peak composite video (factory set default) via 75 ohm BNC connector

Maximum gain +6dB

Maximum lift +12dB at 5MHz

**Relay Contact**

Auxiliaries A, B, C and D: 240V AC at 750mA maximum

Alarm Output relay: 240V Ac at 3A maximum

**Lens Motor drive outputs**

Selectable between 5V DC and 10V DC at 100mA. Outputs have a 1 second slow start.

**Temperature Specifications**

Operational Temperature: -10°C to +50°C

Humidity: 10% to 80% (non-condensing)

Storage Temperature: -20°C to +60°C

Storage Humidity: 10% to 95% (non-condensing)

**Dimensions**

ZR-DC/PCB: Main PCB = 175 x 147mm

PCB fixing centres 144.5 x 114.5mm.

**Weight**

ZR-DC/PCB: approx. 250g

**Baxall Limited**, Stockport, England. Visit our Web site: <http://www.baxall.com>

Baxall Limited reserve the right to make changes to the product and specification of the product without prior notice to the customer.